

5-6. INDEFINITE INTEGRATION

M2-T-29

5-6. INDEFINITE INTEGRATION

- (1) Theorem 1: If f and g are differentiable functions over (a, b) and $f'(x) = g'(x) \forall x \in (a, b)$ then $f(x) = g(x) + c \forall x \in (a, b)$ where c is an arbitrary constant.

Proof: Let $h(x) = f(x) - g(x)$, $x \in (a, b)$.

If $x_1, x_2 \in (a, b)$, $x_1 < x_2$ then h is continuous on $[x_1, x_2]$ and differentiable on (x_1, x_2) .

Also by Mean Value Theorem,

$$h(x_1) - h(x_2) = h'(c)(x_1 - x_2) \text{ where } c \in (x_1, x_2)$$

Thus $c \in (a, b)$.

$$\therefore h'(c) = f'(c) - g'(c) = 0$$

$$\therefore h(x_1) = h(x_2), \forall x_1, x_2 \in (a, b)$$

$$\therefore f(x_1) - g(x_1) = f(x_2) - g(x_2), \forall x_1, x_2 \in (a, b)$$

$\therefore f - g$ is a constant function on (a, b) .

$$\therefore f(x) - g(x) = c, \text{ where } c \in \mathbb{R} \text{ is a constant.}$$

$$\therefore f(x) = g(x) + c \forall x \in (a, b).$$

- (2) Theorem 2: If f and g are integrable over interval $I \subset \mathbb{R}$, then

$$\underline{\int [f(x) + g(x)] dx = \int f(x) dx + \int g(x) dx.}$$

$$\underline{\text{Proof:}} \quad \frac{d}{dx} [\int f(x) dx + \int g(x) dx] = \frac{d}{dx} \int f(x) dx + \frac{d}{dx} \int g(x) dx$$

(Rule of derivatives)

$$= f(x) + g(x)$$

(by definition of integration)

$$\therefore \int [f(x) + g(x)] dx = \int f(x) dx + \int g(x) dx$$

In general, if f_1, f_2, \dots, f_n are integrable over an interval,

$$\text{then } \int [f_1(x) + f_2(x) + \dots + f_n(x)] dx = \int f_1(x) dx + \int f_2(x) dx + \dots + \int f_n(x) dx$$

5 - 6. INDEFINITE INTEGRATION

M2-T-30

(3) Theorem 3: $\int k f(x) dx = k \int f(x) dx$ (where k is const.)

Proof:

$$\frac{d}{dx} k \int f(x) dx = k \frac{d}{dx} \int f(x) dx$$

$$= k f(x) \quad (\text{Rule of derivatives})$$

$$\therefore \int k f(x) dx = k \int f(x) dx \quad (\text{By definition of primitive})$$

(4) Theorem 4: $g: [\alpha, \beta] \rightarrow \mathbb{R}$ is continuous on $[\alpha, \beta]$ and differentiable on (α, β) . $g'(t)$ is continuous on (α, β) and $g'(t) \neq 0, \forall t \in (\alpha, \beta)$.

Range of g is a subset of $[a, b]$ and $f: [a, b] \rightarrow \mathbb{R}$ is continuous. Then substitution $x = g(t)$ gives,

$$\int f(x) dx = \int f[g(t)] g'(t) dt$$

Proof: Since f is continuous on $[a, b]$, $\int f(x) dx$ exists. Since $x = g(t)$ is continuous and $R_g \subset [a, b]$, $f(g(t))$ is defined on $[\alpha, \beta]$ and is continuous on $[\alpha, \beta]$. $g'(t)$ is also continuous on (α, β) and $\int f(g(t)) g'(t) dt$ exists.

$$\text{Let } h(x) = \int f(x) dx. \quad \therefore h'(x) = f(x).$$

Hence h is a differentiable function of x on (a, b) and x is a differentiable function of t on (α, β) . Hence, h is also a differentiable function of t on (α, β) .

$$\therefore \frac{d}{dt} h[g(t)] = h'[g(t)] g'(t) = f[g(t)] g'(t)$$

$$\therefore h[g(t)] = \int f[g(t)] g'(t) dt$$

$$\therefore h(x) = \int f[g(t)] g'(t) dt$$

$$\therefore \int f(x) dx = \int f[g(t)] g'(t) dt$$

As $g'(t)$ is continuous and non-zero, $x = g(t)$ is one-one and hence by $t = g^{-1}(x)$, the function on right-hand side can be converted into a function of x .

5 - 6. INDEFINITE INTEGRATION

M2-T-31

(5) Theorem 5: If $\int f(x) dx = F(x)$, then

$$\int f(ax+b) dx = \frac{1}{a} F(ax+b) \text{ where } f: I \rightarrow \mathbb{R} \text{ is continuous on some interval } I. (a \neq 0)$$

Proof: Let $ax+b = t \therefore x = \frac{1}{a}(t-b) = g(t)$ is continuous and differentiable and $g'(t) = \frac{1}{a} \neq 0$. Also $g'(t)$ is continuous.

$$\frac{dx}{dt} = g'(t) = \frac{1}{a}$$

$$\begin{aligned} \therefore \int f(ax+b) dx &= \int f(t) \frac{dx}{dt} dt = \frac{1}{a} \int f(t) dt \\ &= \frac{1}{a} F(t) = \frac{1}{a} F(ax+b) \end{aligned}$$

(6) Theorem 6: $\int [f(x)]^n f'(x) dx = \frac{[f(x)]^{n+1}}{n+1} + c, n \neq -1$

where $f(x) > 0$ and f, f' are continuous and $f'(x) \neq 0$.

Proof: Let $t = f(x)$. So $\frac{dt}{dx} = f'(x)$

Since $f'(x) \neq 0$ and continuous, $t = f(x)$ is one-one.

$$\begin{aligned} \therefore \int [f(x)]^n f'(x) dx &= \int t^n dt = \frac{t^{n+1}}{n+1} + c \\ &= \frac{[f(x)]^{n+1}}{n+1} + c \end{aligned}$$

(7) Theorem 7: If f is continuous and differentiable and f' is continuous and non-zero, $f(x) \neq 0, x \in [a, b]$, then $\int \frac{f'(x)}{f(x)} dx = \log |f(x)| + c$.

Proof: f' is continuous and non-zero. Hence f is monotonic. Hence $t = f(x) \Rightarrow x = f^{-1}(t) \therefore f'(x) \frac{dx}{dt} = 1$.

$$\begin{aligned} \therefore \int \frac{f'(x)}{f(x)} dx &= \int \frac{f'(x)}{f(x)} \cdot \frac{dx}{dt} dt = \int \frac{dt}{t} = \log |t| + c \\ &= \log |f(x)| + c \end{aligned}$$

5 - 6. INDEFINITE INTEGRATION

M2-T-32

$$(8) \quad \underline{\int \operatorname{cosec} x \, dx = \log |\operatorname{cosec} x - \cot x| = \log \left| \tan \frac{x}{2} \right| + c}$$

Proof: For $\operatorname{cosec} x$ to be defined, $x \neq k\pi$, $k \in \mathbb{Z}$.

$$\therefore \sin x \neq 0 \text{ and } 1 - \cos x \neq 0.$$

$$\therefore \frac{1 - \cos x}{\sin x} = \operatorname{cosec} x - \cot x \neq 0$$

$$\begin{aligned} \text{Now, } \int \operatorname{cosec} x \, dx &= \int \frac{\operatorname{cosec} x (\operatorname{cosec} x - \cot x)}{\operatorname{cosec} x - \cot x} \, dx \\ &= \int \frac{-\operatorname{cosec} x \cot x + \operatorname{cosec}^2 x}{\operatorname{cosec} x - \cot x} \, dx \\ &= \int \frac{\frac{d}{dx} (\operatorname{cosec} x - \cot x)}{\operatorname{cosec} x - \cot x} \, dx \\ &= \log |\operatorname{cosec} x - \cot x| + c \end{aligned}$$

$$\text{Also, } \operatorname{cosec} x - \cot x = \frac{1 - \cos x}{\sin x} = \tan \frac{x}{2}$$

$$\therefore \int \operatorname{cosec} x \, dx = \log |\operatorname{cosec} x - \cot x| = \log \left| \tan \frac{x}{2} \right| + c.$$

$$(9) \quad \underline{\int \sec x \, dx = \log \left| \tan \left(\frac{\pi}{4} + \frac{x}{2} \right) \right| + c = \log |\sec x + \tan x| + c}$$

Proof: For $\sec x$ to be defined, $x \neq (2k+1)\frac{\pi}{2}$, $k \in \mathbb{Z}$.

$$\therefore \cos x \neq 0 \text{ and } 1 + \sin x \neq 0.$$

$$\therefore \frac{1 + \sin x}{\cos x} = \sec x + \tan x \neq 0$$

$$\begin{aligned} \text{Now, } \int \sec x \, dx &= \int \frac{\sec x (\sec x + \tan x)}{\sec x + \tan x} \, dx \\ &= \int \frac{\sec^2 x + \sec x \tan x}{\sec x + \tan x} \, dx \\ &= \int \frac{\frac{d}{dx} (\sec x + \tan x)}{\sec x + \tan x} \, dx \\ &= \log |\sec x + \tan x| + c \end{aligned}$$

$$\text{Also, } \sec x + \tan x = \frac{1 + \tan^2 \frac{x}{2}}{1 - \tan^2 \frac{x}{2}} + \frac{2 \tan \frac{x}{2}}{1 - \tan^2 \frac{x}{2}}$$

5 - 6. INDEFINITE INTEGRATION

M2-T-33

$$= \frac{(1 + \tan^2 x/2)^2}{(1 - \tan^2 x/2)(1 + \tan^2 x/2)} = \frac{1 + \tan^2 \frac{x}{2}}{1 - \tan^2 \frac{x}{2}}$$

$$= \tan(\pi/4 + x/2)$$

$$\therefore \int \sec x dx = \log |\sec x + \tan x| + c = \log \left| \tan\left(\frac{\pi}{4} + \frac{x}{2}\right) \right| + c$$

(10) Rule of Integration by Parts:

If (i) f, g are differentiable on interval $I \subset \mathbb{R}$ and
 (ii) f', g' are continuous on I , then

$$\int f(x) g'(x) dx = f(x) g(x) - \int f'(x) g(x) dx, \quad x \in I.$$

Proof: f and g are differentiable functions of x .

\therefore according to working rules of differentiation,

$$\frac{d}{dx} [f(x) g(x)] = f(x) g'(x) + g(x) f'(x)$$

Now, f, g, f', g' are given to be continuous on $I \subset \mathbb{R}$.

$\therefore fg'$ and $f'g$ are also continuous and hence integrable.

\therefore by definition of integration,

$$f(x) g(x) = \int [f(x) g'(x) + g(x) f'(x)] dx$$

$$= \int f(x) g'(x) dx + \int g(x) f'(x) dx$$

$$\therefore \int f(x) g'(x) dx = f(x) g(x) - \int f'(x) g(x) dx \quad \dots (i)$$

This is the rule of integration by parts.

Now, let $f(x) = u$ and $g'(x) = v$

$$\therefore f'(x) = \frac{du}{dx} \text{ and } g(x) = \int v dx$$

Substituting in (i)

$$\int uv dx = u \int v dx - \int \left[\frac{du}{dx} \int v dx \right] dx \quad \dots (ii)$$

$$(11) \int \sqrt{x^2 + a^2} dx = \frac{x}{2} \sqrt{x^2 + a^2} + \frac{a^2}{2} \log |x + \sqrt{x^2 + a^2}| + c$$

Proof: Let $I = \int \sqrt{x^2 + a^2} dx = \int \sqrt{x^2 + a^2} \cdot 1 dx$

$$\therefore I = \sqrt{x^2 + a^2} \int 1 dx - \int \left[\frac{d}{dx} \sqrt{x^2 + a^2} \cdot \int 1 dx \right] dx$$

5 - 6. INDEFINITE INTEGRATION

M2-T-34

$$\begin{aligned}
 I &= x \sqrt{x^2+a^2} - \int \frac{1}{2\sqrt{x^2+a^2}} \cdot 2x \cdot x \, dx \\
 &= x \sqrt{x^2+a^2} - \int \frac{x^2 \, dx}{\sqrt{x^2+a^2}} \\
 &= x \sqrt{x^2+a^2} - \int \frac{(x^2+a^2) - a^2}{\sqrt{x^2+a^2}} \, dx \\
 &= x \sqrt{x^2+a^2} - \int \sqrt{x^2+a^2} \, dx + a^2 \int \frac{dx}{\sqrt{x^2+a^2}} \\
 &= x \sqrt{x^2+a^2} - I + a^2 \log |x + \sqrt{x^2+a^2}| + 2c \\
 \therefore 2I &= x \sqrt{x^2+a^2} + a^2 \log |x + \sqrt{x^2+a^2}| + 2c \\
 \therefore I &= \frac{x}{2} \sqrt{x^2+a^2} + \frac{a^2}{2} \log |x + \sqrt{x^2+a^2}| + c
 \end{aligned}$$

Similarly, it can be proved that

$$\int \sqrt{x^2-a^2} \, dx = \frac{x}{2} \sqrt{x^2-a^2} - \frac{a^2}{2} \log |x + \sqrt{x^2-a^2}| + c$$

$$(12) \quad \underline{\int \sqrt{a^2-x^2} \, dx = \frac{x}{2} \sqrt{a^2-x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + c \quad (a > 0)}$$

Proof: $I = \int \sqrt{a^2-x^2} \, dx = \int 1 \cdot \sqrt{a^2-x^2} \, dx$

$$\begin{aligned}
 &= \sqrt{a^2-x^2} \int 1 \, dx - \int \left[\frac{d}{dx} \sqrt{a^2-x^2} \int 1 \, dx \right] dx \\
 &= x \sqrt{a^2-x^2} - \int \frac{1}{2\sqrt{a^2-x^2}} \cdot (-2x) \cdot x \, dx \\
 &= x \sqrt{a^2-x^2} - \int \frac{(a^2-x^2) - a^2}{\sqrt{a^2-x^2}} \, dx \\
 &= x \sqrt{a^2-x^2} - \int \sqrt{a^2-x^2} \, dx + a^2 \int \frac{dx}{\sqrt{a^2-x^2}} \\
 &= x \sqrt{a^2-x^2} - I + a^2 \sin^{-1} \frac{x}{a} + 2c \\
 \therefore 2I &= x \sqrt{a^2-x^2} + a^2 \sin^{-1} \frac{x}{a} + 2c \\
 \therefore I &= \frac{x}{2} \sqrt{a^2-x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + c
 \end{aligned}$$

(Note: This result can also be proved by the substitution $x = a \sin \theta$.)

5 - 6. INDEFINITE INTEGRATION

M2-T-35

$$(13) \quad \underline{\int e^x [f(x) + f'(x)] dx = e^x f(x) + c}$$

$$\begin{aligned} \text{Proof: } \int e^x f(x) dx &= f(x) \int e^x dx - \int \left[\frac{d}{dx} f(x) \int e^x dx \right] dx \\ &= e^x f(x) - \int e^x f'(x) dx + c \end{aligned}$$

$$\therefore \int e^x [f(x) + f'(x)] dx = e^x f(x) + c.$$

$$\begin{aligned} (14) \quad \int e^{ax} \sin bx dx &= \frac{e^{ax}}{a^2 + b^2} (a \sin bx - b \cos bx) \\ &= \frac{e^{ax} \sin (bx - \theta)}{\sqrt{a^2 + b^2}} + c \end{aligned}$$

$$\text{where, } \cos \theta = \frac{a}{\sqrt{a^2 + b^2}}, \quad \sin \theta = \frac{b}{\sqrt{a^2 + b^2}}, \quad a, b \neq 0.$$

$$\begin{aligned} \text{Proof: } I &= \int e^{ax} \sin bx dx \\ &= \sin bx \int e^{ax} dx - \int \left[\frac{d}{dx} \sin bx \int e^{ax} dx \right] dx \\ &= \sin bx \cdot \frac{e^{ax}}{a} - b \int \cos bx \cdot \frac{e^{ax}}{a} dx \\ &= \sin bx \cdot \frac{e^{ax}}{a} - \frac{b}{a} \int e^{ax} \cos bx dx \\ \therefore I &= \sin bx \cdot \frac{e^{ax}}{a} - \frac{b}{a} \left[\cos bx \int \frac{e^{ax}}{a} - \int -b \sin bx \cdot \frac{e^{ax}}{a} dx \right] \\ &= \sin bx \cdot \frac{e^{ax}}{a} - \frac{b}{a^2} \cos bx \cdot e^{ax} - \frac{b^2}{a^2} \int e^{ax} \sin bx dx \\ &= \frac{e^{ax}}{a^2} (a \sin bx - b \cos bx) - \frac{b^2}{a^2} I + \left(\frac{a^2 + b^2}{a^2} \right) c \\ \therefore \frac{a^2 + b^2}{a^2} I &= \frac{e^{ax}}{a^2} (a \sin bx - b \cos bx) + \left(\frac{a^2 + b^2}{a^2} \right) c \\ \therefore I &= \frac{e^{ax}}{a^2 + b^2} (a \sin bx - b \cos bx) \quad \dots (i) \end{aligned}$$

$$\text{Now, let } a = r \cos \theta, \quad b = r \sin \theta \quad \therefore r = \sqrt{a^2 + b^2}$$

$$\begin{aligned} \therefore a \sin bx - b \cos bx &= r \cos \theta \sin bx - r \sin \theta \cos bx \\ &= r \sin (bx - \theta) \\ &= \sqrt{a^2 + b^2} \sin (bx - \theta) \end{aligned}$$

5 - 6. INDEFINITE INTEGRATION

M2-T-36

Substituting in (i),

$$\begin{aligned} I &= \frac{e^{ax}}{a^2+b^2} [\sqrt{a^2+b^2} \sin(bx-\theta)] + c \\ &= \frac{e^{ax}}{\sqrt{a^2+b^2}} \sin(bx-\theta) + c \end{aligned}$$

$$\text{where, } \cos \theta = \frac{a}{\sqrt{a^2+b^2}}, \sin \theta = \frac{b}{\sqrt{a^2+b^2}}; a, b \neq 0.$$

Similarly, it can be proved that

$$\begin{aligned} \int e^{ax} \cos bx \, dx &= \frac{e^{ax}}{a^2+b^2} (a \cos bx + b \sin bx) + c \\ &= \frac{e^{ax}}{\sqrt{a^2+b^2}} \cos(bx-\theta) + c \end{aligned}$$

$$\text{where, } \cos \theta = \frac{a}{\sqrt{a^2+b^2}}, \sin \theta = \frac{b}{\sqrt{a^2+b^2}}; a, b \neq 0.$$

7 - 9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

M2 - T - 37

7-9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

(1) Fundamental principle of definite integration:

If the function f is continuous on $[a, b]$ and F is a differentiable function on $[a, b]$ such that

$$F'(x) = f(x), \quad \forall x \in [a, b], \text{ then}$$

$$\int_a^b f(x) dx = F(b) - F(a)$$

(2) Rule of substitution in definite integration:

$\phi : [d, \beta] \rightarrow [a, b]$ is an increasing (or decreasing) function.

$x = \phi(t)$ and $\phi'(t)$, $t \in [d, \beta]$ are continuous and $\phi'(t)$ has constant sign. If $a = \phi(d)$, $b = \phi(\beta)$, then

$$\int_a^b f(x) dx = \int_d^\beta f[\phi(t)] \phi'(t) dt$$

(3) Theorem 1: If f is an even continuous function on $[-a, a]$

$$\int_{-a}^a f(x) dx = 2 \int_0^a f(x) dx \quad (a \in \mathbb{R}^+)$$

Proof: $\int_{-a}^a f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx \quad [\because -a < 0 < a]$

Now, let $I = \int_{-a}^0 f(x) dx$.

Let $x = -t \quad \therefore dx = -dt$

Also $x = -a \Rightarrow t = a$ and $x = 0 \Rightarrow t = 0$

$x = -t$ and $dx/dt = -1$ are continuous on $[-a, a]$ and sign of dx/dt is constant.

$$\therefore I = \int_a^0 f(-t) (-dt) = - \int_a^0 f(-t) dt = \int_0^a f(t) dt \quad (\because f \text{ is even})$$

$$\therefore I = \int_0^a f(x) dx$$

$$\therefore \int_{-a}^a f(x) dx = \int_0^a f(x) dx + \int_0^a f(x) dx = 2 \int_0^a f(x) dx$$

7 - 9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

M2-T-38

(4) Theorem 2 : If f is continuous and odd function on $[-a, a]$

$$\underline{\int_{-a}^a f(x) dx = 0 \quad (a \in \mathbb{R}^+)}$$

Proof : $\int_{-a}^a f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx \quad [\because -a < 0 < a]$

Now, let $I = \int_{-a}^0 f(x) dx$

Let $x = -t \quad \therefore dx = -dt$

Also $x = -a \Rightarrow t = a$ and $x = 0 \Rightarrow t = 0$

$$\therefore I = \int_a^0 f(-t) (-dt) = - \int_a^0 f(-t) dt = \int_0^a f(-t) dt$$

$$= - \int_0^a f(t) dt \quad (\because f \text{ is an odd function})$$

$$= - \int_0^a f(x) dx$$

$$\therefore \int_{-a}^a f(x) dx = - \int_0^a f(x) dx + \int_0^a f(x) dx = 0.$$

(5) Theorem 3 : If f is continuous on $[0, a]$,

$$\underline{\int_0^a f(x) dx = \int_0^a f(a-x) dx}$$

Proof : Let $I = \int_0^a f(a-x) dx$

Let $a-x = t \quad \therefore dx = -dt$

Also, $x=0 \Rightarrow t=a$ and $x=a \Rightarrow t=0$

$$\therefore I = \int_a^0 f(t) (-dt) = - \int_a^0 f(t) dt = \int_0^a f(t) dt$$

$$= \int_0^a f(x) dx$$

$$\therefore \int_0^a f(x) dx = \int_0^a f(a-x) dx$$

(6) Theorem 4 : If f is continuous over $[a, b]$,

$$\underline{\int_a^b f(x) dx = \int_a^b f(a+b-x) dx}$$

Proof : Let $I = \int_a^b f(a+b-x) dx$

Let $a+b-x = t \quad \therefore -dx = dt$

7 - 9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

M2-T-39

Also, $x = a \Rightarrow t = b$ and $x = b \Rightarrow t = a$.

$$\begin{aligned} \therefore I &= \int_b^a f(t) (-dt) = - \int_b^a f(t) dt = \int_a^b f(t) dt \\ &= \int_a^b f(x) dx \end{aligned}$$

$$\therefore \int_a^b f(x) dx = \int_a^b f(a+b-x) dx$$

(7) Theorem 5: If f is continuous on $[0, 2a]$,

$$\int_0^{2a} f(x) dx = \int_0^a f(x) dx + \int_0^a f(2a-x) dx$$

Proof: $\int_0^{2a} f(x) dx = \int_0^a f(x) dx + \int_a^{2a} f(x) dx$
($\because 0 < a < 2a$)

Let $x = 2a - t$ in second integral on R.H.S.

$$\therefore dx = -dt. \text{ Also, } x=a \Rightarrow t=a \text{ and } x=2a \Rightarrow t=0$$

$$\begin{aligned} \therefore \int_a^{2a} f(x) dx &= \int_a^0 f(2a-t) (-dt) = - \int_a^0 f(2a-t) dt \\ &= \int_0^a f(2a-t) dt = \int_0^a f(2a-x) dx \end{aligned}$$

$$\therefore \int_0^{2a} f(x) dx = \int_0^a f(x) dx + \int_0^a f(2a-x) dx$$

Corollary: (i) If $f(2a-x) = f(x)$, $\int_0^{2a} f(x) dx = 2 \int_0^a f(x) dx$

(ii) If $f(2a-x) = -f(x)$, $\int_0^{2a} f(x) dx = 0$

(8) Differential equation:

A functional relation between independent variable x , dependent variable y and its derivatives y_1, y_2, \dots, y_n is called a differential equation. It is denoted by $F(x, y, y_1, y_2, \dots, y_n) = 0$.

If a differential equation is written in the form of a polynomial, the order of the highest order derivative occurring in the equation is called the order of the differential equation and its power is called the degree of the differential equation.

7 - 9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

M2-T-40

Given a differential equation, if we can find a function $y = f(x)$ such that x , y and its derivatives identically satisfy the differential equation, then the function $y = f(x)$ is called the solution of the given differential equation. If the solution contains the constants of integration, it is called the general solution.

The general solution of a differential equation will contain as many constants as the order of the differential equation.

(9) Homogeneous Differential Equations:

If $f(x, y)$ is a function of two variables x and y and it can be written as $x^n \phi(y/x)$ form where $n \in \mathbb{Q}$ and ϕ is a function of one variable $t = y/x$, then f is a homogeneous function in x, y having degree n .

If in the differential equation $Mdx + Ndy = 0$, M and N are homogeneous functions of x, y having degree n , it is said to be a homogeneous differential equation.

In other words, if in first order first degree differential equation, $Mdx + Ndy = 0$, M and N are homogeneous functions of the same degree, that is, the equation can be written as

$$\frac{dy}{dx} = f\left(\frac{y}{x}\right), \text{ it is a homogeneous differential equation.}$$

(10) Solution of homogeneous differential equation:

Let $\frac{dy}{dx} = f\left(\frac{y}{x}\right)$ be a homogeneous differential equation.

To solve such an equation, let $y = vx$

7 - 9. DEFINITE INTEGRALS DIFFERENTIAL EQUATIONS

M2 - T - 41

$$\therefore \frac{dy}{dx} = v + x \frac{dv}{dx}$$

Substituting in differential equation,

$$v + x \frac{dv}{dx} = f(v) \quad \therefore x \frac{dv}{dx} = f(v) - v$$

$$\therefore \frac{dv}{f(v) - v} = \frac{dx}{x} \text{ is of variables separable type.}$$

Integrating $\int \frac{dv}{f(v) - v} = \log|x| + c$ (c is arbitrary const.)

$$\therefore F(v) = \log|x| + c \text{ where, } F(v) = \int \frac{dv}{f(v) - v}$$

Substituting $v = y/x$, we get the solution of the differential equation.

(11) Linear Differential Equation and its solution:

The differential equation of one degree in y and its derivatives is called a linear differential equation.

Let $\frac{dy}{dx} + Py = Q$ be a given linear differential equation of first order, where P, Q are functions of x . We shall consider a special type only where P is a constant.

Multiplying both sides of the equation by $e^{\int P dx} = e^{Px}$,

$$e^{Px} \frac{dy}{dx} + P e^{Px} y = Q e^{Px}$$

$$\text{Now, } e^{Px} \frac{dy}{dx} + P e^{Px} y = \frac{d}{dx} (e^{Px} y)$$

$$\therefore \frac{d}{dx} (e^{Px} y) = Q e^{Px}, \text{ where } Q e^{Px} \text{ is a function of } x \text{ only.}$$

Integrating, $e^{Px} y = \int Q e^{Px} dx + c$ (c is arbitrary constant).

This is the general solution.

10 - 11. PROBABILITY

M2-T-42

10 - 11. PROBABILITY

Definitions :

1) Random experiment :

An experiment for which all of its outcomes are known in advance but which of these outcomes will occur can be determined only after its performance is called a random experiment.

2) Sample space :

The set of all possible outcomes of a random experiment is called a sample space. A sample space is, usually, denoted by the symbol U and its element is denoted by the letter x .

3) Event :

A subset of the sample space U is called an event. It is usually denoted by capital letters A, B, C, D, \dots or subscripted symbols $A_1, A_2, A_3 \dots$

4) Impossible and certain events :

The null set ϕ as typical subset of sample space is called an impossible event. Sample space U is called a certain event.

5) Complementary event :

Let A be an event. Set of all points or elements of U which are not in A is called the complementary event of A . It is denoted by A' or \bar{A} . In set theoretic notation, $A' = \{x \mid x \in U, x \notin A\}$.

Impossible event ϕ and certain event U are complementary events.

10 - 11. PROBABILITY

M2-T-43

6) Union of two events:

Let A and B be events. Set of all elements which are either in A or in B is called the union of two events A and B and is denoted by $A \cup B$. In set theoretic notation, $A \cup B = \{x \in U \mid x \in A \text{ or } x \in B\}$

7) Intersection of two events:

Let A and B be events. Set consisting of all elements which are in A and in B is called the intersection of two events A and B and is denoted by $A \cap B$. In set theoretic notation, $A \cap B = \{x \in U \mid x \in A \text{ and } x \in B\}$.

8) Mutually exclusive events:

Let A and B be events. If $A \cap B = \phi$, then A and B are called mutually exclusive events.

9) Exhaustive events:

Let A and B be events. If $A \cup B = U$, then A and B are called exhaustive events.

10) Mutually exclusive and exhaustive events:

Let A and B be events. If $A \cap B = \phi$ and $A \cup B = U$, then A and B are called mutually exclusive and exhaustive events. Obviously, $B = A' = U - A$.

11) Difference of two events:

Let A and B be events. The set of elements which are in A but not in B is called the difference of two events A and B and is denoted by $A - B$.

Similarly, we can define the event $B - A$. In set theoretic notation, $A - B = \{x \in U \mid x \in A \text{ and } x \notin B\}$

$$B - A = \{x \in U \mid x \in B \text{ and } x \notin A\}.$$

10 - 11. PROBABILITY

M2-T-44

12) Partition of a sample space:

Mutually exclusive and exhaustive events, A_1, A_2, \dots, A_n ($n \geq 2$) form a partition of a sample space U .

13) Elementary events:

Let U be a finite sample space and let $U = \{x_1, x_2, \dots, x_m\}$. Singleton subsets $\{x_i\}$ of U for $i = 1, 2, \dots, m$ are called elementary events.

14) Set Function:

Let R be the set of real numbers and S be the powerset of U . A rule $T: S \rightarrow R$ which assigns a unique element of R to every member of S is called a set function.

15) Additive set function:

Let $T: S \rightarrow R$ be a set function. If for all $A_1 \in S, A_2 \in S$ and $A_1 \cap A_2 = \emptyset$, $T(A_1 \cup A_2) = T(A_1) + T(A_2)$, then T defined on S is called an additive set function.

16) Axiomatic Definition of Probability:

Let U be a finite sample space and S be the power set of U . Let the set function $P: S \rightarrow R$ satisfy the following axioms:

Axiom 1: For every $A \in S$, $P(A) \geq 0$.

Axiom 2: $P(U) = 1$.

Axiom 3: If $A_1 \in S$ and $A_2 \in S$ are any mutually exclusive events then $P(A_1 \cup A_2) = P(A_1) + P(A_2)$.

Set function P defined on S and satisfying the axioms 1, 2 and 3 is called a probability function and for $A \in S$, $P(A)$ is called the probability of event A . The triplet (U, S, P) is called a probability space.

10 - 11. PROBABILITY

M2-T-45

17) Equally likely elementary events:

Let $U = \{x_1, x_2, \dots, x_n\}$ be a finite sample space. If $P(\{x_1\}) = P(\{x_2\}) = \dots = P(\{x_n\})$, then elementary events $\{x_1\}, \{x_2\}, \dots, \{x_n\}$ are called equally likely.

18) Classical definition of probability:

If a sample space associated with a random experiment has n possible elements (or n outcomes) and if k ($0 \leq k \leq n$) out of n elements are favourable to the occurrence of the event A , then $P(A) = \frac{k}{n}$.

19) Conditional probability:

Let A and B be events of the power set S of a finite sample space U and let P be the probability function defined over S . If $P(B) > 0$, then the conditional probability $P(A|B)$ of event A given the event B is defined by

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

If $P(B) = 0$, $P(A|B)$ cannot be defined.

20) Independence of two events:

Let A and B be events with $P(A) > 0$ and $P(B) > 0$.

If the conditional probability $P(A|B)$ of event A given the event B is equal to $P(A)$, i.e., $P(A|B) = P(A)$, then events A and B are said to be independent.

Similarly, $P(B|A) = P(B)$ also implies the same condition. Alternately, if $P(A \cap B) = P(A) \cdot P(B)$, then events A and B are said to be independent events.

21) Independence of More than Two Events:

For more than two events, mathematician Bernstien

10 - 11. PROBABILITY

M2 - T - 46

put forward the concept of two types of independence, namely, pairwise independence and mutual independence.

Pairwise independence:

For three events A_1, A_2 and A_3 with $P(A_i) > 0$ ($i=1, 2, 3$),

$$\text{if } P(A_1 \cap A_2) = P(A_1)P(A_2)$$

$$P(A_2 \cap A_3) = P(A_2)P(A_3)$$

$$P(A_3 \cap A_1) = P(A_3)P(A_1)$$

then events A_1, A_2 and A_3 are said to be pairwise independent.

Mutual independence:

For three events A_1, A_2, A_3 with $P(A_i) > 0$ ($i=1, 2, 3$),

$$\text{if } P(A_1 \cap A_2) = P(A_1)P(A_2)$$

$$P(A_2 \cap A_3) = P(A_2)P(A_3)$$

$$P(A_3 \cap A_1) = P(A_3)P(A_1) \text{ and}$$

$$P(A_1 \cap A_2 \cap A_3) = P(A_1)P(A_2)P(A_3)$$

then events A_1, A_2, A_3 are said to be mutually independent.

22) Random variable:

Let U be a sample space associated with a random experiment. A real valued function defined on U , $X: U \rightarrow \mathbb{R}$ is called a random variable.

23) Probability distribution of random variable:

Let $X: U \rightarrow \mathbb{R}$ be a random variable. Suppose X assumes values in the set $\{x_1, x_2, \dots, x_n\}$ which is a subset of \mathbb{R} . Further suppose that x assumes a value x_i with probability $p(x_i) = P(X = x_i)$. If $p(x_i) \geq 0$, $i = 1, 2, \dots, n$ and $\sum_{i=1}^n p(x_i) = 1$, then the set of real values $\{p(x_1), p(x_2), \dots, p(x_n)\}$ is called a probability distribution of the random variable $\{x_1, x_2, \dots, x_n\}$

10 - 11. PROBABILITY

M2-T-47

Theory:

1) Theorem 1: For impossible event ϕ , $P(\phi) = 0$.

Proof: Events ϕ and U are mutually exclusive and $\phi \cup U = U$. Suppose $A_1 = \phi$ and $A_2 = U$.

Then $P(\phi \cup U) = P(U) = P(\phi) + P(U)$ (\because axiom 3)

$\therefore 1 = P(\phi) + 1$. Hence $P(\phi) = 0$.

2) Theorem 2: If A is any event, $P(A') = 1 - P(A)$.

Proof: Events A and A' are mutually exclusive and $A \cup A' = U$. Hence by axiom 3, we have

$$P(A \cup A') = P(A) + P(A')$$

$$P(A \cup A') = P(U) = 1$$

$$\therefore P(A) + P(A') = 1$$

$$\therefore P(A') = 1 - P(A). \text{ Also, } P(A) = 1 - P(A')$$

3) Theorem 3: If A and B are events and $A \subset B$, then

$$P(B-A) = P(B) - P(A) \text{ and } P(A) \leq P(B)$$

Proof: It is given that $A \subset B$. This is shown in the Venn diagram given below.

Now A and $B-A$ are mutually exclusive events and $A \cup (B-A) = B$

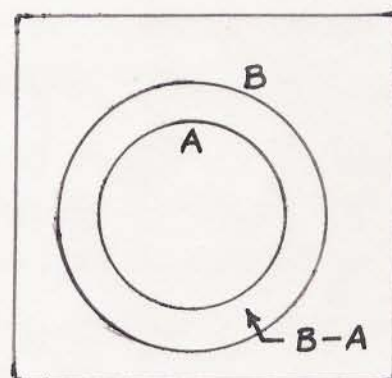
$$\therefore P(B) = P(A) + P(B-A)$$

$$\therefore P(B-A) = P(B) - P(A)$$

For event $B-A$, $P(B-A) \geq 0$

and hence $P(A) \leq P(B)$

Thus for $A \subset B$, $P(A) \leq P(B)$.



Corollary 1: For event A , $0 \leq P(A) \leq 1$.

Proof: Clearly $\phi \subset A$ and $A \subset U$.

10 - 11. PROBABILITY

M2-T-48

According to axiom $P(A) \geq 0$.

$\therefore 0 = P(\emptyset) \leq P(A)$ and $P(A) \leq P(U) = 1$.

Hence, $0 \leq P(A) \leq 1$.

Corollary 2: For any events A and B

$$P(A \cap B') = P(A) - P(A \cap B)$$

Proof: Venn diagram for events A and B

which are not mutually exclusive is drawn. From the Venn diagram,

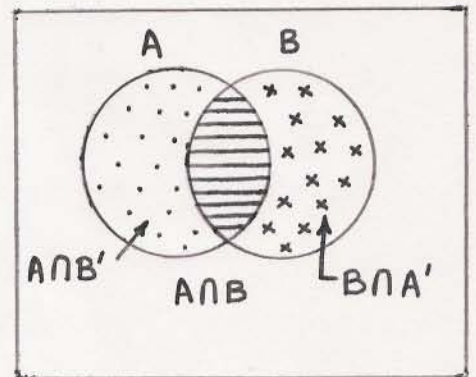
$$A \cap B' = A - (A \cap B)$$

(This result is true even

if A and B are mutually exclusive.)

Since $(A \cap B) \subset A$, we have

$$P(A \cap B') = P(A) - P(A \cap B)$$



4) Theorem 4: If A and B are any events, then

$$P(A \cup B) = P(A) + P(B) - P(A \cap B).$$

Proof: From the above Venn diagram it is clear that events A and $B - A$ are mutually exclusive and $A \cup (B \cap A') = A \cup B$

$$\therefore P(A \cup B) = P(A) + P(B \cap A') \dots \dots \dots (i)$$

Since $B \cap A' = B - (A \cap B)$ and $(A \cap B) \subset B$,

according to theorem 3, we have

$$P(B \cap A') = P(B) - P(A \cap B) \dots \dots \dots (ii)$$

Hence, from (i) and (ii), we have

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

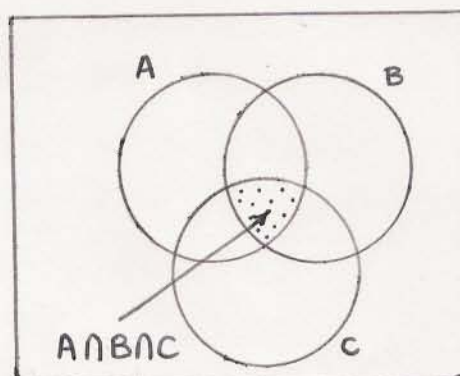
5) Theorem 5: If A, B and C are events, then

$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(B \cap C) - P(C \cap A) + P(A \cap B \cap C).$$

10 - 11. PROBABILITY

M2-T-49

$$\begin{aligned}
 \text{Proof: } P(A \cup B \cup C) &= P(A \cup (B \cap C)) \\
 &= P(A) + P(B \cap C) - P(A \cap (B \cap C)) \\
 &= P(A) + P(B) + P(C) - P(B \cap C) \\
 &\quad - P((A \cap B) \cup (A \cap C)) \\
 &(\because \text{Theorem 4 and} \\
 &\quad \text{distributive law of} \\
 &\quad \text{set operations}).
 \end{aligned}$$



$$\begin{aligned}
 &= P(A) + P(B) + P(C) - P(B \cap C) \\
 &\quad - [P(A \cap B) + P(A \cap C) - P(A \cap B \cap C)] \\
 &= P(A) + P(B) + P(C) - P(A \cap B) - P(B \cap C) - P(C \cap A) + P(A \cap B \cap C).
 \end{aligned}$$

(Note: Theorems 4 and 5 are known as addition theorems of probability).

6) To prove that the set function $P(A|B)$ treated as a function of event A for fixed event B is a probability function on S .

$$\begin{aligned}
 \text{Proof: } (i) \quad P(A \cap B) &\geq 0 \text{ and } P(B) > 0 \\
 \therefore P(A|B) &= \frac{P(A \cap B)}{P(B)} \geq 0
 \end{aligned}$$

Hence, for a fixed event B in S and for any event $A \in S$, $P(A|B) \geq 0$ which satisfies axiom 1 of probability function.

(ii) If $A = U$, then by definition of $P(A|B)$,

$$P(U|B) = \frac{P(U \cap B)}{P(B)} = \frac{P(B)}{P(B)} = 1.$$

This satisfies axiom 2 of probability function.

(iii) If A_1 and A_2 are mutually exclusive events in S , then by definition of conditional probability,

$$P(A_1 \cup A_2 | B) = \frac{P[(A_1 \cup A_2) \cap B]}{P(B)}$$

By distributive law of set operations,

$$(A_1 \cup A_2) \cap B = (A_1 \cap B) \cup (A_2 \cap B)$$

10 - 11. PROBABILITY

M2-T-50

Since events A_1 and A_2 are mutually exclusive, events $A_1 \cap B$ and $A_2 \cap B$ are also mutually exclusive. Hence, by axiom 3 of probability,

$$P[(A_1 \cup A_2) \cap B] = P(A_1 \cap B) + P(A_2 \cap B)$$

$$\begin{aligned} \therefore P(A_1 \cup A_2 | B) &= \frac{P(A_1 \cap B) + P(A_2 \cap B)}{P(B)} \\ &= \frac{P(A_1 \cap B)}{P(B)} + \frac{P(A_2 \cap B)}{P(B)} \end{aligned}$$

Thus, for mutually exclusive events A_1 and A_2 ,

$$P(A_1 \cup A_2 | B) = P(A_1 | B) + P(A_2 | B).$$

Hence, conditional probability satisfies the axiom 3.

7) $P(A|B) = P(A \cap B) / P(B) \Rightarrow P(A \cap B) = P(B)P(A|B)$

Similarly, $P(A \cap B \cap C) = P(A) \cdot P(B|A) \cdot P(C|A \cap B)$

This is called the multiplication rule of probability.

8) Theorem 7 : Bayes' Rule : Let B_1 and B_2 be mutually exclusive and exhaustive events. If $P(B_i)$ and $P(A|B_i)$ for $i = 1, 2$ are given and $P(A) \neq 0$, then

$$P(B_i | A) = \frac{P(B_i)P(A|B_i)}{P(B_1)P(A|B_1) + P(B_2)P(A|B_2)}, \quad i = 1, 2$$

Proof : By definition of ~~classical~~ ^{conditional} probability,

$$P(B_i | A) = P(A \cap B_i) / P(A) \dots \dots (i)$$

Now, by multiplication rule of probability and theorem 6,

$$P(A \cap B_i) = P(B_i)P(A|B_i) \dots \dots \dots (ii)$$

$$P(A) = P(B_1)P(A|B_1) + P(B_2)P(A|B_2) \dots (iii)$$

Using results (ii) and (iii) in (i), we get

$$P(B_i | A) = \frac{P(B_i)P(A|B_i)}{P(B_1)P(A|B_1) + P(B_2)P(A|B_2)} \quad i = 1, 2$$

For three mutually exclusive and exhaustive events B_1, B_2, B_3 ,

$$P(B_i | A) = \frac{P(B_i)P(A|B_i)}{P(B_1)P(A|B_1) + P(B_2)P(A|B_2) + P(B_3)P(A|B_3)} \quad i = 1, 2, 3.$$

10 - 11. PROBABILITY

M2-T-51

9) Theorem 6. Let B_1 and B_2 be mutually exclusive and exhaustive events and $P(B_1) \neq 0$ and $P(B_2) \neq 0$. If an event A occurs under the influence of any one of the two events B_1 and B_2 , then

$$P(A) = P(B_1)P(A|B_1) + P(B_2)P(A|B_2)$$

Proof: According to the conditions of the theorem,
 $U = B_1 \cup B_2$ and hence $A = A \cap U = A \cap (B_1 \cup B_2)$
 $= (A \cap B_1) \cup (A \cap B_2)$.

Since B_1 and B_2 are mutually exclusive events, $A \cap B_1$ and $A \cap B_2$ are also mutually exclusive events.

Hence $P(A) = P(A \cap B_1) + P(A \cap B_2) \dots \dots$ (i)

According to multiplication rule of probability,

$$P(A \cap B_1) = P(B_1)P(A|B_1), \text{ and}$$

$$P(A \cap B_2) = P(B_2)P(A|B_2) \dots \dots$$
 (ii)

Using relation (ii) in (i), we get

$$P(A) = P(B_1)P(A|B_1) + P(B_2)P(A|B_2)$$

This result can be extended for three mutually exclusive and exhaustive events as follows:

$$P(A) = P(B_1)P(A|B_1) + P(B_2)P(A|B_2) + P(B_3)P(A|B_3).$$

As B_1 and B_2 are mutually exclusive and exhaustive, taking $B_1 = B$ and $B_2 = B'$, we can write

$$P(A) = P(B)P(A|B) + P(B')P(A|B')$$